VM-01



Gear-Wheel Volume Sensor for Viscous Fluids, **for OEM Applications**

Description: The VM-01 series of the flowmeter measuring sensor consists of a par of toothed wheels which is driven by the flow of fluid according to the working principle of a gear-wheel pump. The bearing for the measuring sensor is designed as a radial and axial sliding contact bearing (VM-01)

of toothed wheels which is driven by the flow of fluid according to the working principle of a gear-wheel pump. The bearing for the measuring sensor is designed as a radial and axial sliding contact bearing (VM-01.2: ball bearing). The gear-wheel movement is scanned by means of a magneto-resistive sensor that is hermetically separated from the measuring chamber. The gear-wheel diameter of the VM-01 is ideal due to its low resistance to flow and especially low sound level.

Application:

The gear-wheel flowmeters of the VM-01 series are mainly used for measuring consumption, control of filling operations and for monitoring lubrication points. Due to their small dimensions and, particularly, due to the low pricing, they are suitable for OEM applications.

/ For media with viscosities between 20. . .4000 cSt / Excellent price/performance ratio / Aluminium housing, steel gear-wheels / Low pressure drop / High pressure resistance / Convenient dim. for assembly





/ Flow / Gear-Wheel Flowmeters

Flow-Measurement and -monitoring

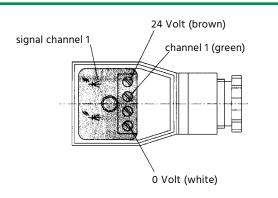
Versions and Ranges:

Туре	Op. range (l/min)	Viscosity range (cSt)	Connection	Geo. tooth volume cm ³	Resolution (pulse/l)
VM-01.0	0.024	204000	G 1/4" IG	0.04	25,000
VM-01.1	0.2510	204000	G 3/8″ IG	0.2	5,000
VM-01.2	0.1616	203000	G 3/8" IG	0.245	4,082
VM-01.3	165	204000	G 3/4" IG	2	500
VM-01.4	1200	204000	G 1" IG	5.222	191.5

Materials:

Туре	Housing	Gear-wheels	Bearing
VM-01.0.1	aluminium	st. steel 1.4462	ball bearing
VM-01.0.2	st. steel 1.4404	st. steel 1.4462	ball bearing
VM-01.1.1	aluminium (hartcoated)	st. steel 1.4462	plastic sliding bearing
VM-01.1.2	st. steel 1.4404	st. steel 1.4462	plastic sliding bearing
VM-01.2	aluminium	steel	ball bearing
VM-01.3	aluminium (hartcoated)	steel 1.7139	multi-layer sliding bearing
VM-01.4	aluminium (hartcoated)	steel 1.7139	ball bearing

Electrical Connection:



Technical Specifications:

Pressure /		max. Pressure	Pressure peak
	VM-01.0.1:		240 bar
	VM-01.0.2:	160 bar	190 bar
	VM-01.1:	160 bar	200 bar
	VM-01.2:	160 bar	200 bar
	VM-01.3:	160 bar	200 bar
	VM-01.4:	80 bar	100 bar
Temperature range /	-10+80°C		
Accuracy /	VM-01.0:	± 2.0% ab	20mm²/s
	VM-01.1:	± 3.0% ab	20mm²/s
	VM-01.2:	± 0.3% ab	20mm²/s
	VM-01.3:	± 2.5% ab	20mm²/s
	VM-01.4:	± 1.0% ab	20mm²/s
Weight /	VM-01.0.1:	0.5 kg	
	VM-01.0.2:	1.2 kg	
	VM-01.1.1:	0.5 kg	
	VM-01.1.2:	1.2 kg	
	VM-01.2:	0.7 kg	
	VM-01.3:	1.9 kg	
	VM-01.4:	6.0 kg	
Supply voltage /	12 30 VDC, polarity-reversal-proof		
Output signal /	rectangular pulses, \geq 0,8 U _B ,		
	scan ratio 1:1 (± 15%)		
Protection class /	IP 65		
Power consumption /	0.9 $W_{max.}$		
Mounting position /	beliebig		
Sound pressure level /	L _A = < 60dB (A)		

Ordering Codes:

Order number	VM-01.	1.	2
VM-01 Gear-Wheel Volume Sensor	J		
Operating ranges /			
0 = 0.024 I/min			
1 = 0.2510 l/min			
2 = 0.1616 l/min			
3 = 165 l/min			
4 = 1200 l/min			
Material /			-
1 = aluminium			

2 = stainless steel (VM-01.0 and VM-01.1 only)



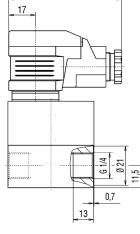
Dimensions in mm:

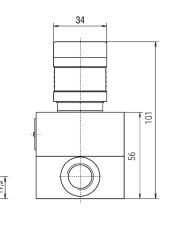
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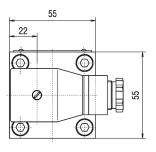


VM-01.1

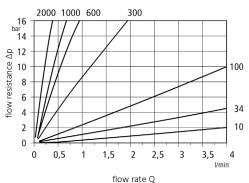
VM-01.2







VM-01.0 Δ **p-curve** – flow resistance at viscosity



72

G 3/8

13

flow rate Q

VM-01.1 Δp -curve – flow resistance at viscosity

0.3 ± 0.2

1000

600

300

100

34

10

10 l/min

17

8

bar

10

8

6

4

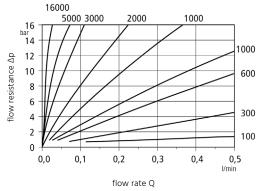
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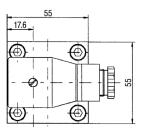
0

0 1 2 3 4 5 6 7 8 9

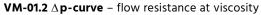
flow resistance Δp

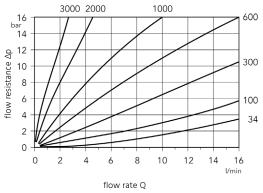
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VM-01.2: same as VM-01.1, however, housing 55 x 65 mm, height 108 mm



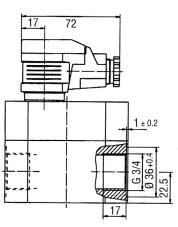


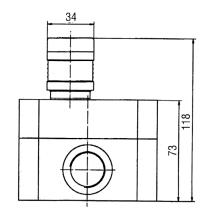


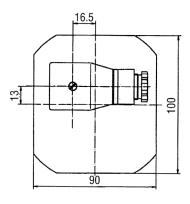
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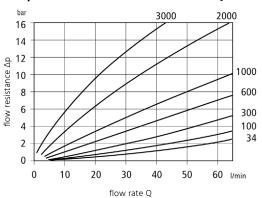
VM-01.3



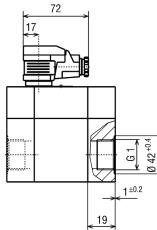


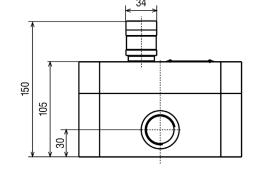


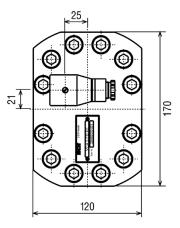
VM-01.3 Δp -curve – flow resistance at viscosity











VM-01.4 Δ **p-curve** – flow resistance at viscosity

